

Study of a System of Convection-Diffusion-Reaction

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Abstract In this article, we are interested in the study of the existence of weak solutions of boundary value problem

$$\text{for the nonlinear elliptic system } \begin{cases} -\operatorname{div}(a_1(x, v(x) \nabla u)) - \operatorname{div}(G_1(x, \varphi_1(v))) = f(x, u, v) \text{ in } \Omega, \\ -\operatorname{div}(a_2(x, u(x) \nabla v)) - \operatorname{div}(G_2(x, \varphi_2(u))) = g(x, u, v) \text{ in } \Omega, \\ u = v = 0 \text{ on } \partial\Omega \end{cases}$$

where Ω is a bounded domain in \mathbb{R}^N and a_1, a_2 are continuous functions. We use the Leray-Schauder degree theory under not linear for the three reasons: the terms of diffusion, convection and reaction, and the following condition on the last term f

$$\text{and } g : \begin{cases} \lim_{s, |t| \rightarrow \infty} f(x, s, t) = \zeta_1^+, \quad \lim_{-s, |t| \rightarrow \infty} f(x, s, t) = \zeta_1^-, \\ \zeta_1^-, \zeta_1^+ \in L^2(\Omega), \quad \zeta_1^- \leq f(x, s, t) \leq \zeta_1^+, \end{cases} \quad \text{and } \begin{cases} \lim_{s, |t| \rightarrow \infty} g(x, s, t) = \zeta_2^+, \quad \lim_{-s, |t| \rightarrow \infty} g(x, s, t) = \zeta_2^-, \\ \zeta_2^-, \zeta_2^+ \in L^2(\Omega), \quad \zeta_2^- \leq g(x, s, t) \leq \zeta_2^+. \end{cases}$$

Keywords: topological degree, elliptic systems, homotopy

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1. Introduction

This article is devoted to presenting the results of existence of solution for a nonlinear elliptic systems of partial differential equations, in a bounded domain of \mathbb{R}^N , with zero Dirichlet boundary conditions. These results are obtained by using Leray-Schauders topological degree and some tools of functional analysis. The corresponding scalar case considered in [6] which has shown the existence of solutions to the problem $Au = \alpha u^+ - \beta u^- + f(x, u) + h$, where A is a self-adjoint operator with compact resolvent in $L^2(\Omega)$, $f(\cdot, \cdot)$ maps $\Omega \times \mathbb{R}$ into \mathbb{R} , such that $\lim_{s \rightarrow \infty} \frac{f(x, s)}{s} = 0$ and $[\alpha, \beta] \cap \sigma(A) = \emptyset$, (λ a simple eigenvalue of A). In this paper we establish the existence of weak solutions for the problem

$$\begin{cases} \begin{cases} -\operatorname{div}(a_1(x, v(x) \nabla u)) \\ -\operatorname{div}(G_1(x, \varphi_1(v))) \end{cases} = f(x, u, v) \text{ in } \Omega, \\ \begin{cases} -\operatorname{div}(a_2(x, u(x) \nabla v)) \\ -\operatorname{div}(G_2(x, \varphi_2(u))) \end{cases} = g(x, u, v) \text{ in } \Omega, \\ u = v = 0 \text{ on } \partial\Omega, \end{cases} \quad (1.1)$$

Where Ω is a bounded domain in \mathbb{R}^N ($N \geq 1$) with smooth boundary $\partial\Omega$ and a_1, a_2 are continuous functions satisfying the condition below:

$$\begin{cases} \alpha_i, \beta_i > 0 \\ \alpha_i \leq a_i(x, s) \leq \beta_i \quad \forall s \in \mathbb{R} \text{ a.e } x \in \Omega \text{ for } i = 1, 2. \end{cases} \quad (1.2)$$

In the case where $a_1 = a_2 = 1, \varphi_1 = \varphi_2 = 0$, we have the existence of the solution if l is a simple eigenvalue of $(-\Delta)$, see [9]. And in [10] studied the case where l is not an eigenvalue i.e $\lambda \notin \sigma(-\Delta)$, $\sigma(-\Delta)$ denotes the spectrum of $-\Delta$. The case no resonance was treated by Lakhel and Khodja (see [11]).

For the rest of this article, we suppose that

$$\begin{cases} G_i \in C^1(\bar{\Omega}, \mathbb{R}^N), \\ \operatorname{div} G_i = 0 \text{ for } i = 1, 2 \end{cases} \quad (1.3)$$

and

$$\begin{cases} \varphi_i \in C(\mathbb{R}, \mathbb{R}), \\ |\varphi_i(s)| \leq C_i |s| \text{ for } i = 1, 2 \end{cases} \quad (1.4)$$

where C_i , are real positive constants.

We assume that $f, g : \Omega \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ are continuous functions satisfying the carathéodory conditions, and verifying also the growth restriction defined below:

$$\begin{cases} |f(x, s, t)| \leq C'_1(1 + |s| + |t|), \\ |g(x, s, t)| \leq C'_2(1 + |s| + |t|), \end{cases} \quad (1.5)$$

where C_1', C_2' are real positive constants.

$$\begin{cases} \lim_{s, |t| \rightarrow \infty} f(x, s, t) = \zeta_1^+, & \lim_{-s, |t| \rightarrow \infty} f(x, s, t) = \zeta_1^-, \\ \zeta_1^-, \zeta_1^+ \in L^2(\Omega), & \zeta_1^- \leq f(x, s, t) \leq \zeta_1^+, \end{cases} \quad (1.6)$$

and

$$\begin{cases} \lim_{s, |t| \rightarrow \infty} g(x, s, t) = \zeta_2^+, & \lim_{-s, |t| \rightarrow \infty} g(x, s, t) = \zeta_2^-, \\ \zeta_2^-, \zeta_2^+ \in L^2(\Omega), & \zeta_2^- \leq g(x, s, t) \leq \zeta_2^+. \end{cases} \quad (1.7)$$

Theorem 1.1. *Under the assumptions (1.2), (1.3), (1.4), (1.5), (1.6) and (1.7), there exists a solution to the problem (1.1).*

2. Preliminaries

Let us consider the space

$$U = H_0^1(\Omega) \times H_0^1(\Omega),$$

which is a Banach space endowed with the norm

$$\|(u, v)\|_U^2 = \|(u)\|_{H_0^1(\Omega)}^2 + \|(v)\|_{H_0^1(\Omega)}^2$$

such as U^* its dual, and let us take $V = L^2(\Omega) \times L^2(\Omega)$. In the sequel, $\|\cdot\|_{L^2(\Omega)}$ and $\|\cdot\|_{H_0^1(\Omega)}$ will denote the usual norms on $L^2(\Omega)$ and $H_0^1(\Omega)$ respectively. Recalling that the operator A , given by

$$Au = -\Delta u,$$

$$D(A) = \{u \in H_0^1(\Omega), \Delta u \in L^2(\Omega)\},$$

defines an inverse compact on $L^2(\Omega)$ and his spectrum is formed by the sequence $(\lambda_k)_{k \in \mathbb{N}^*}$ such that $|\lambda_k| \rightarrow +\infty$ and λ_1 the first eigenvalue is positive. Throughout this paper, we denote by λ a simple eigenvalue of A , φ is an eigenfunction associated to λ normalized in $L^2(\Omega)$, Pr designates the orthogonal projection of V on $(\varphi^\perp)^2$ (φ^\perp is the orthogonal of φ in $L^2(\Omega)$). We recall the following proposition proved by T.Gallouet and O.Kavian (see [5]).

We give now a definition of weak solution.

Definition 2.1. We say $(u, v) \in \mathcal{U}$ is a weak solution for the system (1.1) if for any $(\varphi, \psi) \in U$ we have

$$\begin{cases} \left[\int_{\Omega} a_1(v) \nabla_u \cdot \nabla \varphi dx \right. \\ \left. + \int_{\Omega} G_1 \varphi_1(v) \cdot \nabla \varphi dx \right] = \int_{\Omega} f(u, v) \varphi dx, \\ \left[\int_{\Omega} a_2(u) \nabla_v \cdot \nabla \psi dx \right. \\ \left. + \int_{\Omega} G_2 \varphi_2(u) \cdot \nabla \psi dx \right] = \int_{\Omega} g(u, v) \psi dx. \end{cases} \quad (2.1)$$

We write the problem in the form

$$\begin{cases} (u, v) \in \mathcal{U}, \\ \int_{\Omega} a_1(v) \nabla_u \cdot \nabla \varphi dx + \int_{\Omega} a_2(u) \nabla_v \cdot \nabla \psi dx \\ = \langle L(u, v), (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}} \forall (\varphi, \psi) \in \mathcal{U}, \end{cases}$$

where $L(u, v)$ is, for $(u, v) \in V$, the element of \mathcal{U}^* defined by

$$\begin{aligned} & \langle L(u, v), (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}} \\ &= - \int_{\Omega} G_1 \varphi_1(v) \cdot \nabla \varphi dx - \int_{\Omega} G_2 \varphi_2(u) \cdot \nabla \psi dx \\ &+ \int_{\Omega} f(u, v) \varphi dx - \int_{\Omega} g(u, v) \psi dx. \end{aligned}$$

From (1.3), (1.4) and (1.5), it is clear that the application $L(u, v)$ is continuous to V in \mathcal{U}^* . For $S \in \mathcal{U}^*$, the linear problem

$$\begin{cases} (w_1, w_2) \in \mathcal{U}, \\ \int_{\Omega} a_1(v) \nabla_{w_1} \cdot \nabla \varphi dx + \int_{\Omega} a_2(u) \nabla_{w_2} \cdot \nabla \psi dx \\ = \langle S, (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}}, \end{cases} \quad (2.2)$$

has a unique solution $(w_1, w_2) \in (H_0^1(\Omega))^2$. We note the operator $B_{u,v}$ who at S in \mathcal{U}^* associates (w_1, w_2) solution of (2.2). To $H_0^1(\Omega) \hookrightarrow L^2(\Omega)$ is compact, we deduced that the operator $B_{u,v}$ is compact to \mathcal{U}^* in V .

The problem (1.1) is equivalent to solving the fixed point problem $(u, v) = B_{u,v}(L(u, v))$. So we show through topological degree, the following problem has a solution

$$\begin{cases} (u, v) \in V, \\ (u, v) = B_{u,v}(L(u, v)). \end{cases}$$

For $t \in [0, 1]$, we put $H(t, u, v) = B_{u,v}(tL(u, v)) \in V$. The mapping H is defined to $[0, 1] \times V$ in V . For $R > 0$, let us put

$$B_R = \{(u, v) \in V \text{ such that } \|(u, v)\|_V \leq R\}.$$

Let us show now that

$$\{H(t, u, v), t \in [0, 1], (u, v) \in B_R\} \text{ is relatively compact } \in V.$$

Let $R > 0$, we assume that $\|(u, v)\|_V \leq R$. We have $L(u, v) \in \mathcal{U}^*$, and

$$\begin{aligned} & \langle L(u, v), (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}} \\ &= - \int_{\Omega} G_1 \varphi_1(v) \cdot \nabla \varphi dx - \int_{\Omega} G_2 \varphi_2(u) \cdot \nabla \psi dx \\ &+ \int_{\Omega} f(u, v) \varphi dx + \int_{\Omega} g(u, v) \psi dx. \end{aligned}$$

We want to estimate $\langle L(u, v), (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}}$.

$$\begin{aligned}
 & \langle L(u, v), (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}} \\
 & \leq \|G_1\|_\infty \|\varphi_1(v)\|_{L^2(\Omega)} \|\varphi\|_{H_0^1(\Omega)} \\
 & \quad + \|G_2\|_\infty \|\varphi_2(u)\|_{L^2(\Omega)} \|\psi\|_{H_0^1(\Omega)} \\
 & \quad + \|f(u, v)\|_{L^2(\Omega)} \|\varphi\|_{L^2(\Omega)} + \|g(u, v)\|_{L^2(\Omega)} \|\psi\|_{L^2(\Omega)} \\
 & \leq \|G_1\|_\infty C_1 \|v\|_{L^2(\Omega)} \|\varphi\|_{H_0^1(\Omega)} + \|G_2\|_\infty C_2 \|u\|_{L^2(\Omega)} \|\psi\|_{H_0^1(\Omega)} \\
 & \quad + C_\Omega C'_1 \left(1 + \|u\|_{L^2(\Omega)} + \|v\|_{L^2(\Omega)}\right) \|\varphi\|_{H_0^1(\Omega)} \\
 & \quad + C_\Omega C'_2 \left(1 + \|u\|_{L^2(\Omega)} + \|v\|_{L^2(\Omega)}\right) \|\psi\|_{H_0^1(\Omega)} \\
 & \leq \|G_1\|_\infty C_1 \|(u, v)\|_V \|(\varphi, \psi)\|_{\mathcal{U}} + \|G_2\|_\infty C_2 \|(u, v)\|_V \|(\varphi, \psi)\|_{\mathcal{U}} \\
 & \quad + C_\Omega C'_1 \left(1 + \|(u, v)\|_V + \|(u, v)\|_V\right) \|(\varphi, \psi)\|_{\mathcal{U}} \\
 & \quad + C_\Omega C'_2 \left(1 + \|(u, v)\|_V + \|(u, v)\|_V\right) \|(\varphi, \psi)\|_{\mathcal{U}} \\
 & \leq \left(\|G_1\|_\infty C_1 R + \|G_2\|_\infty C_2 R \right. \\
 & \quad \left. + C'_1 C_\Omega (1 + 2R) + C'_2 C_\Omega (1 + 2R) \right) \|(\varphi, \psi)\|_{\mathcal{U}},
 \end{aligned}$$

where C_Ω depends only on Ω (and is given by the Poincar inequality). So $\forall t \in [0, 1]$

$$\begin{aligned}
 & t \|L(u, v)\|_{\mathcal{U}^*} \\
 & \leq \|G_1\|_\infty C_1 R + \|G_2\|_\infty C_2 R \\
 & \quad + C'_1 C_\Omega (1 + 2R) + C'_2 C_\Omega (1 + 2R).
 \end{aligned}$$

Let $H(t, u, v) = B_{u,v}(tL(u, v)) = (w_1, w_2)$ and show that there \bar{R} depending only on $R, G_i, C_\Omega, C_i, C'_i, \alpha_i$, for $i = 1, 2$ such that

$$\|H(t, u, v)\|_{\mathcal{U}} \leq \bar{R}.$$

By definition, (w_1, w_2) is a solution of

$$\begin{cases}
 (w_1, w_2) \in \mathcal{U}, \\
 \int_\Omega a_1(v) \nabla w_1 \cdot \nabla \varphi dx + \int_\Omega a_2(u) \nabla w_2 \cdot \nabla \psi dx \\
 = \langle tL(u, v), (\varphi, \psi) \rangle_{\mathcal{U}^*, \mathcal{U}}.
 \end{cases} \quad (2.3)$$

Taking $\varphi = w_1, \psi = w_2$ in (2.3) we obtain

$$\begin{aligned}
 & \min(\alpha_1, \alpha_2) \|(w_1, w_2)\|_{\mathcal{U}}^2 \\
 & \leq \|tL(u, v)\|_{\mathcal{U}^*, \mathcal{U}} \|(w_1, w_2)\|_{\mathcal{U}} \leq \tilde{R} \|(w_1, w_2)\|_{\mathcal{U}},
 \end{aligned}$$

with

$$\begin{aligned}
 \tilde{R} & = \|G_1\|_\infty C_1 R + \|G_2\|_\infty C_2 R \\
 & \quad + C'_1 C_\Omega (1 + 2R) + C'_2 C_\Omega (1 + 2R).
 \end{aligned}$$

We have

$$\|H(t, u, v)\|_{\mathcal{U}} = \|(w_1, w_2)\|_{\mathcal{U}} \leq \frac{\tilde{R}}{\min(\alpha_1, \alpha_2)} = \bar{R}.$$

By Rellich theorem, we deduce that the set $\{H(t, u, v), t \in [0, 1], (u, v) \in \bar{B}_R\}$ is relatively compact in V , therefore $H(t, u, v): [0, 1] \times V \rightarrow V$ is compact.

We now show that H is continuous.

Proposition 2.1. The mapping H is continuous to $[0, 1] \times \bar{B}_R$ in \bar{B}_R .

Proof. Let (t_n, u_n, v_n) converge to (t, u, v) in $[0, 1] \times V$.

We want to show that

$$H(t_n, u_n, v_n) \rightarrow H(t, u, v) \text{ in } V.$$

Let

$$(w_{n,1}, w_{n,2}) = H(t_n, u_n, v_n),$$

and

$$(w_1, w_2) = H(t, u, v).$$

To show that

$$(w_{n,1}, w_{n,2}) \rightarrow (w_1, w_2) \text{ in } V,$$

seeking to pass to the limit on the following equation:

$$\begin{cases}
 (w_{n,1}, w_{n,2}) \in \mathcal{U}, \\
 \int_\Omega a_1(v_n) \nabla w_{n,1} \cdot \nabla \varphi dx + \int_\Omega a_2(u_n) \nabla w_{n,2} \cdot \nabla \psi dx \\
 = -t_n \int_\Omega G_1 \varphi_1(v_n) \cdot \nabla \varphi dx - t_n \int_\Omega G_2 \varphi_2(u_n) \cdot \nabla \psi dx \\
 + t_n \int_\Omega f(u_n, v_n) \varphi dx - t_n \int_\Omega g(u_n, v_n) \psi dx.
 \end{cases} \quad (2.4)$$

We know that $(w_{n,1}, w_{n,2})$ is bounded in \mathcal{U} , because (u_n, v_n) is bounded in V (this is shown in the previous step: $\|(u_n, v_n)\|_V \leq R$ then $\|(w_{n,1}, w_{n,2})\|_{\mathcal{U}} \leq \bar{R}$.)

The sequence $(w_{n,1}, w_{n,2})_{n \in \mathbb{N}}$ is bounded in \mathcal{U} , therefore

$$\begin{aligned}
 & (w_{n,1}, w_{n,2}) \rightarrow (\tilde{w}_1, \tilde{w}_2) \text{ in } \mathcal{U} \text{ weak and} \\
 & (w_{n,1}, w_{n,2}) \rightarrow (\tilde{w}_1, \tilde{w}_2) \text{ in } V, (u_n, v_n) \rightarrow (u, v) \text{ a.e.} \\
 & \text{and } \exists H, G \in L^2(\Omega); |u_n| \leq H \text{ a.e and } |v_n| \leq G \text{ a.e.}
 \end{aligned} \quad (2.5)$$

Let $(\varphi, \psi) \in \mathcal{U}$; as $a_1(v_n) \rightarrow a_1(v)$ a.e therefore

$$a_1(v_n) \nabla \varphi \rightarrow a_1(v) \nabla \varphi \text{ a.e,}$$

and

$$|a_1(v_n) \nabla \varphi| \leq \beta_1 \nabla \varphi,$$

we have

$$a_1(v_n) \nabla \varphi \rightarrow a_1(v) \nabla \varphi \text{ in } L^2(\Omega).$$

But $\nabla w_{n,1} \rightarrow \nabla \tilde{w}_1$ in $(L^2(\Omega))^N$ weak. We have

$$\int_\Omega a_1(v_n) \nabla w_{n,1} \cdot \nabla \varphi dx \rightarrow \int_\Omega a_1(v) \nabla \tilde{w}_1 \cdot \nabla \varphi dx.$$

Similarly we have

$$\int_{\Omega} a_2(u_n) \nabla w_{n,2} \nabla \psi dx \rightarrow \int_{\Omega} a_2(u) \nabla \tilde{w}_2 \nabla \psi dx.$$

Then we notice that

$$\varphi_1(v_n) \rightarrow \varphi_1(v) \text{ a.e.}$$

and

$$|\varphi_1(v_n)| \leq C_1 |v_n| \leq C_1 G,$$

thanks to Lebesgue's convergence theorem, we deduce that

$$\varphi_1(v_n) \rightarrow \varphi_1(v) \text{ in } L^2(\Omega),$$

and

$$\int_{\Omega} G_1 \varphi_1(v_n) \cdot \nabla \varphi dx \rightarrow \int_{\Omega} G_1 \varphi_1(v) \cdot \nabla \varphi dx.$$

Similarly we have

$$\int_{\Omega} G_2 \varphi_2(u_n) \cdot \nabla \psi dx \rightarrow \int_{\Omega} G_2 \varphi_2(u) \cdot \nabla \psi dx.$$

Finally for the last term,

$$f(u_n, v_n) \rightarrow f(u, v) \text{ a.e.}$$

By dominated convergence (from (1.5) and (2.5)) we have

$$f(u_n, v_n) \rightarrow f(u, v) \text{ in } L^2(\Omega),$$

and consequently

$$\int_{\Omega} f(u_n, v_n) \varphi dx \rightarrow \int_{\Omega} f(u, v) \varphi dx.$$

Similarly we have

$$\int_{\Omega} g(u_n, v_n) \psi dx \rightarrow \int_{\Omega} g(u, v) \psi dx.$$

Passing to the limit in (2.4), we obtain

$$\begin{aligned} & \int_{\Omega} a_1(v) \nabla \tilde{w}_1 \nabla \varphi dx + \int_{\Omega} a_2(u) \nabla \tilde{w}_2 \nabla \psi dx \\ &= -t \int_{\Omega} G_1 \varphi_1(v) \cdot \nabla \varphi dx - t \int_{\Omega} G_2 \varphi_2(u) \cdot \nabla \psi dx \\ &+ t \int_{\Omega} f(u, v) \varphi dx + t \int_{\Omega} g(u, v) \psi dx, \end{aligned}$$

and therefore $(\tilde{w}_1, \tilde{w}_2) = H(t, u, v) = (w_1, w_2)$.

As $(w_{n,1}, w_{n,2}) \rightarrow (w_1, w_2)$ in V where $(w_{n,1}, w_{n,2}) = H(t_n, u_n, v_n)$ and $(w_1, w_2) = H(t, u, v)$, then the mapping H is continuous.

3. A Priori Bounds for Solutions of (1.1)

Let $t \in [0, 1]$, and $(u, v) = H(t, u, v) = tB_{u,v}(L(u, v))$, that is to say

$$\begin{cases} (u, v) \in \mathcal{U}, \\ \int_{\Omega} a_1(v) \nabla u \nabla \varphi dx + \int_{\Omega} a_2(u) \nabla v \nabla \psi dx \\ = -t \int_{\Omega} G_1 \varphi_1(v) \cdot \nabla \varphi dx - t \int_{\Omega} G_2 \varphi_2(u) \cdot \nabla \psi dx \\ + t \int_{\Omega} f(u, v) \varphi dx + t \int_{\Omega} g(u, v) \psi dx, \quad \forall (\varphi, \psi) \in \mathcal{U}. \end{cases} \quad (3.1)$$

For $s \in \mathbb{R}$, we put $\Phi_i(s) = \int_0^s \varphi_i(\zeta) d\zeta$ (Φ_i is a primitive of φ_i , for $i = 1, 2$). As $(u, v) \in (H_0^1(\Omega))^2$, It is not difficult to show that $\Phi_i(u) \in W_0^{1,1}(\Omega)$ (resp $\Phi_2(v) \in W_0^{1,1}(\Omega)$) and

$$\begin{cases} \int_{\Omega} G_1 \varphi_1(u) \cdot \nabla u dx = \int_{\Omega} G_1 \cdot \nabla \Phi_1(u) dx, \\ \int_{\Omega} G_2 \varphi_2(v) \cdot \nabla v dx = \int_{\Omega} G_2 \cdot \nabla \Phi_2(v) dx. \end{cases}$$

For (1.3), we have

$$\begin{cases} \int_{\Omega} G_1 \varphi_1(u) \cdot \nabla u dx = \int_{\Omega} G_1 \cdot \nabla \Phi_1(u) dx \\ = - \int_{\Omega} \operatorname{div} G_1 \cdot \Phi_1(u) dx = 0, \\ \int_{\Omega} G_2 \varphi_2(v) \cdot \nabla v dx = \int_{\Omega} G_2 \cdot \nabla \Phi_2(v) dx \\ = - \int_{\Omega} \operatorname{div} G_2 \cdot \Phi_2(v) dx = 0. \end{cases}$$

Taking $u = \varphi$, $v = \psi$ in (3.1). By assumptions (1.2), (1.3), (1.4), (1.5) and (1.6), we have

$$\frac{\min(\alpha_1, \alpha_2)}{\alpha} \|(u, v)\|_{\mathcal{U}}^2 \leq \int_{\Omega} |f(u, v)u| dx + \int_{\Omega} |g(u, v)v| dx.$$

Lemma 3.1. *There exist $R > 0$ such that for all $t \in [0, 1]$ and all $(u, v) \in V$,*

$$(u, v) - H(t, u, v) = 0 \Rightarrow \|(u, v)\|_V < R.$$

Proof. To prove this lemma we assume by contradiction, that for all $R > 0$ there exists $(t, u, v) \in [0, 1] \times V$ such that

$$(u, v) - H(t, u, v) = 0 \text{ and } \|(u, v)\|_V < R.$$

In other words, we can find a sequence $(t_n, u_n, v_n) \in [0, 1] \times V$ such that

$$(u_n, v_n) - H(t_n, u_n, v_n) = 0 \text{ and } \|(u_n, v_n)\|_V < n. \quad (3.2)$$

Taking

$$(\tilde{u}_n, \tilde{v}_n) = \left(\frac{u_n}{\|(u_n, v_n)\|_V}, \frac{v_n}{\|(u_n, v_n)\|_V} \right),$$

we have

$$\|\tilde{u}_n, \tilde{v}_n\|_V = 1,$$

and

$$\alpha \|\tilde{u}_n, \tilde{v}_n\|_{\mathcal{U}}^2 \leq \int_{\Omega} \frac{f(u_n, v_n)}{\|(u_n, v_n)\|_V} \tilde{u}_n dx + \int_{\Omega} \frac{g(u_n, v_n)}{\|(u_n, v_n)\|_V} \tilde{v}_n dx.$$

For (1.5), we have

$$\begin{aligned} & \alpha \|\tilde{u}_n, \tilde{v}_n\|_{\mathcal{U}}^2 \\ & \leq \int_{\Omega} \frac{C'_1(1 + |u_n| + |v_n|)}{\|(u_n, v_n)\|_V} |\tilde{u}_n| dx + \int_{\Omega} \frac{C'_2(1 + |u_n| + |v_n|)}{\|(u_n, v_n)\|_V} |\tilde{v}_n| dx \end{aligned}$$

$$\begin{aligned}
 &\leq \int_{\Omega} \frac{C'_1 |\tilde{u}_n|}{\|(u_n, v_n)\|_V} dx + C'_1 \int_{\Omega} |\tilde{u}_n| |\tilde{u}_n| dx + C'_1 \int_{\Omega} |\tilde{v}_n| |\tilde{u}_n| dx \\
 &+ \int_{\Omega} \frac{C'_2 |\tilde{v}_n|}{\|(u_n, v_n)\|_V} dx + C'_2 \int_{\Omega} |\tilde{u}_n| |\tilde{v}_n| dx + C'_1 \int_{\Omega} |\tilde{v}_n| |\tilde{v}_n| dx \\
 &\leq \frac{1}{\|(u_n, v_n)\|_V} \int_{\Omega} (C'_1 |\tilde{u}_n| + C'_2 |\tilde{v}_n|) dx \\
 &\quad + 2 \max(C'_1, C'_2) \int_{\Omega} |\tilde{u}_n, \tilde{v}_n|^2 dx \\
 &\leq \frac{1}{\|(u_n, v_n)\|_V} \left(C'_1 \|\tilde{u}_n\|_{L^2(\Omega)} + C'_2 \|\tilde{v}_n\|_{L^2(\Omega)} \right) \\
 &\quad + 2 \max(C'_1, C'_2) \|\tilde{u}_n, \tilde{v}_n\|_V^2 \\
 &\leq \frac{1}{\|(u_n, v_n)\|_V} \left(C'_1 \|\tilde{u}_n, \tilde{v}_n\|_V + C'_2 \|\tilde{v}_n, \tilde{v}_n\|_V \right) \\
 &\quad + 2 \max(C'_1, C'_2) \\
 &\leq \frac{\max(C'_1, C'_2)}{\|(u_n, v_n)\|_V} + 2 \max(C'_1, C'_2),
 \end{aligned}$$

Moreover, by (3.2) we have

$$\frac{\max(C'_1, C'_2)}{\|(u_n, v_n)\|_V} \leq \frac{\max(C'_1, C'_2)}{n} \leq \max(C'_1, C'_2).$$

Then

$$\|\tilde{u}_n, \tilde{v}_n\|_{\mathcal{U}}^2 \leq k, \text{ such that } k = \frac{3 \max(C'_1, C'_2)}{\alpha},$$

that is, $\|\tilde{u}_n, \tilde{v}_n\|_{\mathcal{U}}^2$ is bounded in \mathcal{U} .

Since $(\tilde{u}_n, \tilde{v}_n) \in (H_0^1(\Omega))^2$ and the embedding $(H_0^1(\Omega) \hookrightarrow L^2(\Omega))$ is compact, we can extract a subsequence $(\tilde{u}_n, \tilde{v}_n)$, still denoted by $(\tilde{u}_n, \tilde{v}_n)$, which converges in V . Let (\tilde{u}, \tilde{v}) be the limit of $(\tilde{u}_n, \tilde{v}_n)$ in V . We have therefore $\|(u_n, v_n)\|_V = 1$ (which give $\tilde{u} \neq 0$, and $\tilde{v} \neq 0$). We also have

$$(\tilde{u}_n, \tilde{v}_n) \rightarrow (\tilde{u}, \tilde{v}) \text{ a.e.} \tag{3.3}$$

$$|\tilde{u}_n| \leq H \text{ and } |\tilde{v}_n| \leq G, \text{ with } H, G \in L^2(\Omega).$$

Finally, using the Poincare inequality, there is C_{Ω} , depending only on Ω such that

$$\begin{aligned}
 \frac{\alpha}{C_{\Omega}^2} &= \frac{\alpha}{C_{\Omega}^2} \|(u_n, v_n)\|_V^2 \leq \alpha \|\tilde{u}_n, \tilde{v}_n\|_{\mathcal{U}}^2 \\
 &\leq \int_{\Omega} \frac{|f(u_n, v_n)|}{\|(u_n, v_n)\|_V} |\tilde{u}_n| dx + \int_{\Omega} \frac{|g(u_n, v_n)|}{\|(u_n, v_n)\|_V} |\tilde{v}_n| dx.
 \end{aligned}$$

Let us put

$$Z_n = \int_{\Omega} \frac{|f(u_n, v_n)| |\tilde{u}_n|}{\|(u_n, v_n)\|_V} dx + \int_{\Omega} \frac{|g(u_n, v_n)| |\tilde{v}_n|}{\|(u_n, v_n)\|_V} dx.$$

and now we show that $Z_n \rightarrow 0$ when $n \rightarrow \infty$, which is impossible since Z_n is reduced by constant α / C_{Ω}^2 which is strictly positive.

Show that

$$\begin{cases} \frac{f(u_n, v_n) |\tilde{u}_n|}{\|(u_n, v_n)\|_V} \rightarrow 0 \text{ a.e in } \Omega, \\ \frac{g(u_n, v_n) |\tilde{v}_n|}{\|(u_n, v_n)\|_V} \rightarrow 0 \text{ a.e in } \Omega, \end{cases}$$

with domination (in $L^1(\Omega)$), we have by the dominated convergence theorem that $Z_n \rightarrow 0$ when $n \rightarrow \infty$.

We first show dominance.

From (1.5) and (3.3), we have

$$\begin{aligned}
 \left| \frac{f(u_n, v_n)}{\|(u_n, v_n)\|_V} \right| &\leq \frac{C'_1 (1 + |u_n| + |v_n|)}{\|(u_n, v_n)\|_V} \\
 &\leq C'_1 + C'_1 |\tilde{u}_n| + C'_1 |\tilde{v}_n| \leq C'_1 + C'_1 H + C'_1 G, \\
 \left| \frac{g(u_n, v_n)}{\|(u_n, v_n)\|_V} \right| &\leq \frac{C'_2 (1 + |u_n| + |v_n|)}{\|(u_n, v_n)\|_V} \\
 &\leq C'_2 + C'_2 |\tilde{u}_n| + C'_2 |\tilde{v}_n| \leq C'_2 + C'_2 H + C'_2 G.
 \end{aligned}$$

Then

$$\begin{cases} \left| \frac{f(u_n, v_n)}{\|(u_n, v_n)\|_V} \tilde{u}_n \right| \leq (C'_1 + C'_1 H + C'_1 G) H \in L^1(\Omega), \\ \left| \frac{g(u_n, v_n)}{\|(u_n, v_n)\|_V} \tilde{v}_n \right| \leq (C'_2 + C'_2 H + C'_2 G) G \in L^1(\Omega). \end{cases}$$

We now show the convergence a.e.

We have

$$(\tilde{u}_n, \tilde{v}_n) \rightarrow (\tilde{u}, \tilde{v}) \text{ a.e.}$$

Let $x \in A$. From the hypothesis (1.6) and (1.7) it follows that

Case I

If $\tilde{u}(x) > 0$ and $\tilde{v}(x) > 0$, therefore $\tilde{u}(x) \cdot \tilde{v}(x) > 0$ (resp if $\tilde{u}(x) < 0$ and $\tilde{v}(x) < 0$), $\tilde{u}_n(x) \rightarrow \tilde{u}(x)$ and $\tilde{v}_n(x) \rightarrow \tilde{v}(x)$ but

$$\lim_{n \rightarrow \pm\infty} \|u_n, v_n\|_V = \pm\infty$$

therefore $u_n(x) = \tilde{u}_n(x) \|u_n, v_n\|_V \rightarrow \pm\infty$ and

$$v_n(x) = \tilde{v}_n(x) \|u_n, v_n\|_V \rightarrow \pm\infty.$$

$$\begin{cases} \frac{f(u_n(x), v_n(x))}{\|u_n, v_n\|_V} \tilde{u}_n(x) = \frac{f(u_n(x), v_n(x)) v_n(x)}{v_n(x) \|u_n, v_n\|_V} \tilde{u}_n(x) \\ = \frac{f(u_n(x), v_n(x))}{v_n(x)} \tilde{u}_n(x) \cdot \tilde{v}_n(x) \xrightarrow{n \rightarrow \infty} 0, \\ \frac{g(u_n(x), v_n(x))}{\|u_n, v_n\|_V} \tilde{v}_n(x) = \frac{g(u_n(x), v_n(x)) u_n(x)}{u_n(x) \|u_n, v_n\|_V} \tilde{v}_n(x) \\ = \frac{g(u_n(x), v_n(x))}{u_n(x)} \tilde{u}_n(x) \cdot \tilde{v}_n(x) \xrightarrow{n \rightarrow \infty} 0. \end{cases}$$

Case II

If $\tilde{u}(x) > 0$ and $\tilde{v}(x) > 0$, therefore $\tilde{u}(x) \cdot \tilde{v}(x) < 0$ (resp if $\tilde{u}(x) < 0$ and $\tilde{v}(x) > 0$), $\tilde{u}_n(x) \rightarrow \tilde{u}(x)$ and $\tilde{v}_n(x) \rightarrow \tilde{v}(x)$ but

$$\lim_{n \rightarrow \pm\infty} \|u_n, v_n\|_V = \pm\infty$$

therefore $u_n(x) = \tilde{u}_n(x) \|u_n, v_n\|_V \rightarrow \pm\infty$ and

$$v_n(x) = \tilde{v}_n(x) \|u_n, v_n\|_V \rightarrow \pm\infty.$$

$$\left\{ \begin{aligned} \frac{f(u_n(x), v_n(x))}{\|u_n, v_n\|_V} \tilde{u}_n(x) &= \frac{f(u_n(x), v_n(x)) \tilde{v}_n(x)}{\tilde{v}_n(x) \|u_n, v_n\|_V} \tilde{u}_n(x) \\ &= \frac{f(u_n(x), v_n(x))}{v_n(x)} \tilde{u}_n(x) \cdot \tilde{v}_n(x) \xrightarrow{n \rightarrow \infty} 0, \\ \frac{g(u_n(x), v_n(x))}{\|u_n, v_n\|_V} \tilde{v}_n(x) &= \frac{g(u_n(x), v_n(x)) \tilde{u}_n(x)}{\tilde{u}_n(x) \|u_n, v_n\|_V} \tilde{v}_n(x) \\ &= \frac{g(u_n(x), v_n(x))}{u_n(x)} \tilde{u}_n(x) \cdot \tilde{v}_n(x) \xrightarrow{n \rightarrow \infty} 0. \end{aligned} \right.$$

Case III

If $\tilde{u}(x) = \tilde{v}(x) = 0$

$$\begin{aligned} & \left| \frac{f(u_n(x), v_n(x))}{\|u_n, v_n\|_V} \tilde{u}_n(x) \right| \\ & \leq \frac{C'_1 (1 + |u_n(x)| + |v_n(x)|)}{\|u_n, v_n\|_V} |\tilde{u}_n(x)| \\ & \leq (C'_1 + C'_1 |\tilde{u}_n(x)| + C'_1 |\tilde{v}_n(x)|) |\tilde{u}_n(x)| \\ & \rightarrow 0 \text{ because } \tilde{u}(x) = 0, \\ & \left| \frac{g(u_n(x), v_n(x))}{\|u_n, v_n\|_V} \tilde{v}_n(x) \right| \\ & \leq \frac{C'_2 (1 + |u_n(x)| + |v_n(x)|)}{\|u_n, v_n\|_V} |\tilde{v}_n(x)| \\ & \leq (C'_2 + C'_2 |\tilde{u}_n(x)| + C'_2 |\tilde{v}_n(x)|) |\tilde{v}_n(x)| \\ & \rightarrow 0 \text{ because } \tilde{v}(x) = 0. \end{aligned}$$

In summary we have

$$\left\{ \begin{aligned} \frac{f(u_n, v_n)}{\|u_n, v_n\|_V} \tilde{u}_n &\rightarrow 0 \text{ a.e.} \\ \frac{g(u_n, v_n)}{\|u_n, v_n\|_V} \tilde{v}_n &\rightarrow 0 \text{ a.e.} \end{aligned} \right.$$

It was also shown that $\lim_{n \rightarrow +\infty} Z_n = 0$, this is contradiction with $Z_n \geq \alpha / C_\Omega^2$ for all $n \in \mathbb{N}^*$. We have shown that there exists $R > 0$ such that

$$(u, v) = H(t, u, v) \Rightarrow \|u_n, v_n\|_V < R.$$

Now, we give the proof of our main result.

Proof. of Theorem (1.1). We have no solution to the equation $(u, v) - H(t, u, v) = 0$ on the edge of the ball B_R such that $B(0, R) = (u, v) \in V, \|u_n, v_n\|_V < R$.

By invariance of the topological degree we have

$$t \in [0, 1], \text{deg}(H(t, \dots), B(0, R), 0),$$

is constant.

In particular $t = 0$. By the homotopy invariance property, we have

$$\text{deg}(H(t, \dots), B(0, R), 0) = \text{deg}(H(1, \dots), B(0, R), 0) = 1$$

We infer the existence of $(u, v) \in B(0, R)$ as $(u, v) - H(1, u, v) = 0$.

Therefore (u, v) is a solution of (1.1) (and theorem(1.1) is shown).

4. Conclusion

We have discussed in this article the conditions of existence for a nonlinear elliptic system. This problem has been treated by Leray-Schauder degree theory, the latter is a more tool powerful, more general and often even easier to use. The problem proposed in this paper is a generalization of working of T. Gallouët (see [1,5,6]).

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